Probabilistic \mathcal{EL}^{++} with Nominals and Concrete Domains

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Abstract

We present \mathcal{MEL}^{++} (M denotes Markov logic networks) an extension of the log-linear description logics \mathcal{EL}^{++} -LL with concrete domains, nominals, and instances. We use Markov logic networks (MLNs) in order to find the most probable, classified and coherent \mathcal{EL}^{++} ontology from an \mathcal{MEL}^{++} knowledge base. In particular, we develop a novel way to deal with concrete domains by extending MLN's cutting plane inference (CPI) algorithm.

1 Introduction

In description logics (DLs) a concrete domain is a construct that can be used to define new classes by specifying restrictions on attributes that have literal values (as opposed to relationships to other concepts). Practical applications of DLs usually require concrete properties with values from a fixed domain, such as strings or integers, supporting built-in predicates. For DLs that are extended with concrete domains. there exist partial functions mapping objects of the abstract domain to values of the concrete domain, and can be used for building complex concepts. Concrete domains can be used to construct complex concepts as for instance, the axiom $Teenager \equiv Person \sqcap \exists age. (\geq, 13) \sqcap \exists age. (\leq, 19) \text{ defines}$ a teenager as a person whose age is at least 13 and at most 19. In DLs, concrete domains are also known as datatypes. Several probabilistic extensions of DLs opt to exclude datatypes while, in fact, it is an essential feature as several knowledge extraction tools produce weighted rules or axioms that contain concrete data values. Reasoning over these data either to infer new knowledge or to verify correctness is indispensable. Additionally, recent advances in information extraction have paved the way for the automatic construction and growth of large, semantic knowledge bases from different sources. However, the very nature of these extraction techniques entails that the resulting knowledge bases may contain a significant amount of incorrect, incomplete, or even inconsistent (i.e., uncertain) knowledge, which makes efficient reasoning and query answering over this kind of uncertain data a challenge. To address these issues, there exist ongoing studies on probabilistic knowledge bases.

The study of extending DLs to handle uncertainty and vagueness has gained momentum recently. There have been several proposals to add probabilities to various DLs. Probabilistic DLs can be classified in several dimensions. One possible classification is on the reasoning mechanism used: Markov logic networks (MLNs), Bayesian networks, and probabilistic reasoning. There exist some studies that employ MLNs to extend various DLs. The study in [Lukasiewicz et al., 2012] extends \mathcal{EL}^{++} with probabilistic uncertainty based on the annotation of axioms using MLNs. The main focus of this work is ranking queries in descending order of probability of atomic inferences which is different from the objective of this paper. Another study in [Niepert *et al.*, 2011], presents a probabilistic extension of the DL \mathcal{EL}^{++} without nominals and concrete domains in MLN in order to find the most probable coherent ontology. In doing so, they have developed a reasoner for probabilistic OWL-EL called ELOG [Noessner and Niepert, 2011]. In this study, we extend this work in order to deal with concrete domains in addition to nominals and instances. In databases, MLNs have been used to create a probabilistic datalog called Datalog+/-. It is an extension of datalog that allows to express ontological axioms by using rule-based constraints [Gottlob et al., 2013]. The probabilistic extension of Datalog+/- uses MLNs as the underlying probabilistic semantics. The focus of this work is on scalable threshold query answering which is different from that of this

Other literatures extend DLs with Bayesian networks. Some notable works include: an extension of \mathcal{EL} with Bayesian networks called \mathcal{BEL} is presented in [Ceylan and Penaloza, 2014]. They study the complexity of reasoning under \mathcal{BEL} to show that reasoning is intractable. However, their work does not discuss probabilities in the ABox and concrete domains are excluded. On the other hand, in [d'Amato et~al., 2008], they added uncertainty to DL-Lite based on Bayesian networks. Additionally, they have shown that satisfiability test and query answering in probabilistic DL-Lite can be reduced to satisfiability test and query answering in the DL-Lite family. Further, it is proved that satisfiability checking and union of conjunctive query answering can be done in LogSpace in the data complexity.

Numerous literatures studied probabilistic reasoning for different probabilistic DLs. For instance, [Jung and Lutz, 2012] proposes a framework for querying probabilistic instance data in the presence of an OWL 2 QL ontology and provides the data complexity of computing answer probabilities in this framework. In [Gutiérrez-Basulto et al., 2011], they established the complexity of subsumption for a probabilistic variant of the DL \mathcal{EL} . They apply probabilities only to concepts. The complexity of concept subsumption in these settings is ExpTime-hard. Probabilistic extensions of expressive description logics SHIF(D) and SHOIN(D) are studied in [Lukasiewicz, 2008]. Probabilistic knowledge can be expressed both in the TBox and ABox. These logics are based on probabilistic lexicographic entailment from probabilistic default reasoning [Lukasiewicz, 2002] as underlying probabilistic reasoning formalism. Further, Probabilistic \mathcal{ALC} is introduced in [Heinsohn, 1994]. It allows uncertainty to be expressed in the TBox but does not allow probabilities in conceptual and relational assertions. It is based on probabilistic reasoning in probabilistic logics. For further information, we refer the reader to [Heinsohn, 1994] and the references therein. Lastly, the pioneering work of Jaeger [Jaeger, 1994] proposes a probabilistic extension of ALC, which allows for terminological probabilistic knowledge about concepts and roles and about concept instances, respectively, but does not support assertional probabilistic knowledge about role instances (although a possible extension in this direction is mentioned). The uncertainty reasoning formalism in [Jaeger, 1994] is essentially based on probabilistic reasoning in probabilistic logics, as the one in [Heinsohn, 1994], but coupled with cross-entropy minimization to combine terminological probabilistic knowledge with assertional probabilistic knowledge.

As discussed above, most of the studies that involve extending description logics to deal with uncertainty by using either Bayesian or Markov logic networks often excluded concrete domains. This is partly due to either the lack of supporting features or the difficulty in dealing with them. In this paper, we study a novel way of dealing with uncertainty involving concrete domains. In addition, we provide an extension to \mathcal{EL}^{++} -LL with nominals, instances, and concrete domains.

Preliminaries 2

In this section, we present a brief summary of: \mathcal{EL}^{++} , Markov logic networks, integer linear programs, and \mathcal{EL}^{++} -LL. For a detailed discussion on these subjects, we refer the reader to [Baader et al., 2005; Richardson and Domingos, 2006; Schrijver, 1998; Niepert et al., 2011] and the references therein.

 \mathcal{EL}^{++} is the description logic underlying the OWL 2 profile OWL-EL.

Syntax

Given a set of concept names N_{C} , role names N_{R} , individuals N_I , and feature names N_F , \mathcal{EL}^{++} concepts and roles are formed according to the following syntax:

$$C ::= \top \mid \bot \mid A \mid C \cap D \mid \exists R.C \mid \{a\} \mid \exists F.r$$

A concept in \mathcal{EL}^{++} is either a top, bottom concept, an atomic concept or a complex concept (formed by conjunction and existential restriction). Given a datatype restriction r = (o, v)and $x \in \mathcal{D}$, we say that x satisfies r and write r(x) iff $(x, v) \in o$, where $o \in \{<, \le, >, \ge, =\}$, o is interpreted as the standard relation on real numbers, and $\mathcal{D} \subseteq \mathbb{R}$ is a concrete domain [Despoina et al., 2011]. In this work, we consider only numerical concrete domains (also known as datatypes). Additionally, in order to ensure that reasoning remains polynomial, concrete domains must satisfy a condition called padmissibility. This restriction guarantees that satisfiability of concrete domains can be solved in polynomial time, and that concept disjunction cannot be expressed using concrete concepts [Baader et al., 2005]. As an example consider ≤ and \geq predicates for integers, this allows to express $A \sqsubseteq B \sqcup C$ by fromulating the axioms $A \sqsubseteq \exists R.(\leq,5), \exists R.(\leq,2) \sqsubseteq B$ and $\exists R.(\geq,2) \sqsubseteq C$. Thus, allowing both \leq and \geq has the same effect as extending \mathcal{EL}^{++} with disjunction, which is well known to cause intractability [Despoina et al., 2011]. In [Despoina et al., 2011], it has been shown that these restrictions can be significantly relaxed without loosing tractability. This work can take advantage of these relaxations to support more features. An \mathcal{EL}^{++} TBox contains a set of GCI (General Concept Inclusion) axioms, i.e., $C \sqsubseteq D$, as well as role inclusion axioms, i.e., $R_1 \circ \cdots \circ R_k \sqsubseteq R$.

Semantics

The semantics of \mathcal{EL}^{++} concepts and roles is given by an interpretation function $\mathcal{I}=(\Delta^{\mathcal{I}},\mathcal{I})$ which consists of a nonempty (abstract) domain $\Delta^{\mathcal{I}}$ and a mapping \mathcal{I} that assigns to each atomic concept $A\in \mathrm{N_C}$ a subset of $\Delta^{\mathcal{I}}$, to each abstract role $R\in \mathrm{N_R}$ a subset of $\Delta^{\mathcal{I}}\times\Delta^{\mathcal{I}}$, to each concrete relation $F\in \mathrm{N_F}$ a subset of $\Delta^{\mathcal{I}}\times\mathcal{D}$, and to each individual $a\in \mathrm{N_I}$ an element of $\Delta^{\mathcal{I}}$. The mapping \mathcal{I} is extended to all concepts and roles as follows:

$$(\top)^{\mathcal{I}} = \Delta^{\mathcal{I}}$$

$$(\perp)^{\mathcal{I}} = \emptyset$$

$$(\{a\})^{\mathcal{I}} = \{a^{\mathcal{I}}\}$$

$$(C \sqcap D)^{\mathcal{I}} = C^{\mathcal{I}} \cap D^{\mathcal{I}}$$

$$(\exists R.C) = \{x \in \Delta^{\mathcal{I}} \mid \exists y \in \Delta^{\mathcal{I}} : (x,y) \in R^{\mathcal{I}} \land y \in C^{\mathcal{I}}\}$$

$$(\exists F.r)^{\mathcal{I}} = \{x \in \Delta^{\mathcal{I}} \mid \exists v \in \mathcal{D} : (x,v) \in F^{\mathcal{I}}\}$$

$$(C \sqsubseteq D)^{\mathcal{I}} = C^{\mathcal{I}} \subseteq D^{\mathcal{I}}$$

$$(R_1 \circ \cdots \circ R_k \sqsubseteq R)^{\mathcal{I}} = R_1^{\mathcal{I}} \circ \cdots \circ R_k^{\mathcal{I}} \subseteq R^{\mathcal{I}}$$

Knowledge about specific objects can be expressed using concept and role assertions of the form C(a) and R(a, b). The axioms and assertions are contained in the TBox and ABox, respectively, which together form a knowledge base (KB). An \mathcal{EL}^{++} knowledge base (or ontology) $\mathcal{O} = (\mathcal{T}, \mathcal{A})$ consists of a set \mathcal{T} of general concept inclusion axioms (TBox) and role inclusion axioms, and possibly a set A of assertional axioms (ABox). A concept name C in an ontology \mathcal{O} , is unsatisfiable iff, for each interpretation \mathcal{I} of \mathcal{O} , $C^{\mathcal{I}} = \emptyset$. An ontology \mathcal{O} is

incoherent iff there exists an unsatisfiable concept name C in \mathcal{O} , i.e., $C \models \bot$ [Flouris et al., 2006].

To simplify the transformation probabilistic \mathcal{EL}^{++} KB into FOL, we first obtain the *normal* form of the KB in such a way that satisfiability is preserved [Baader *et al.*, 2005; Krötzsch, 2011]. An \mathcal{EL}^{++} KB is in *normal* form its axioms are in the following form:

$$C(a) \quad R(a,b) \quad A \sqsubseteq \bot$$

$$\top \sqsubseteq C \quad A \sqsubseteq \{c\} \quad \{a\} \sqsubseteq \{c\}$$

$$A \sqsubseteq C \quad A \sqcap B \sqsubseteq C \quad \exists R.A \sqsubseteq C$$

$$A \sqsubseteq \exists R.B \quad R_1 \sqsubseteq R_2 \quad R_1 \circ R_2 \sqsubseteq R$$

$$A \sqsubseteq \exists F.r \quad \exists F.r \sqsubseteq A$$

where $A,B,C \in N_C,R,R_1,R_2 \in N_R,F \in N_F,\ r$ is a datatype restriction, and $a,b,c \in N_I$.

It is possible to provide a probabilistic extension of \mathcal{EL}^{++} using MLNs. An \mathcal{EL}^{++} KB can be seen as a set of hard constraints on the set of possible interpretations: if an interpretation violates even one axiom or assertion, it has zero probability. The basic idea in MLNs is to soften these constraints, i.e., when an interpretation violates one axiom or assertion in the KB it is less probable, but not impossible. The fewer axioms an interpretation violates, the more probable it becomes. Each axiom and assertion has an associated weight that reflects how strong a constraint is: the higher the weight, the greater the difference in log probability between an interpretation that satisfies the axiom and one that does not, other things being equal [Richardson and Domingos, 2006].

2.2 Markov Logic Networks

Markov Logic Networks (MLNs) combine Markov networks and first-order logic (FOL) by attaching weights to first-order formulas and viewing these as templates for features of Markov networks [Richardson and Domingos, 2006]. An MNL L is a set of pairs (F_i, w_i) where F_i is a formula in FOL and w_i is a real number representing a weight. Together with a finite set of constants C, it defines a Markov Network $M_{L,C}$, where $M_{L,C}$ contains one node for each possible grounding of each predicate appearing in L. The value of the node is 1 if the ground predicate is true, and 0 otherwise. The probability distribution over possible worlds x specified by the ground Markov network $M_{L,C}$ is given by:

$$P(X = x) = \frac{1}{Z} \exp\left(\sum_{i=1}^{F} w_i n_i(x)\right)$$

where F is the number of formulas in the MLN and $n_i(x)$ is the number of true groundings of F_i in x. The groundings of a formula are formed simply by replacing its variables with constants in all possible ways. The *Herbrand Universe H* for an MLN L is the set of all terms that can be constructed from the constants in L. The *Herbrand Base* HB is often defined as the set of all ground predicates (atoms) that can be constructed using the predicates in L and the terms in H. In this paper we focus on MLNs whose formulas are function-free clauses.

In order to compute a maximum a-posteriori (MAP) state of an MLN, we formulate the problem as an integer linear program (ILP) using the cutting plane inference algorithm.

Integer Linear Program (ILP)

An integer linear program (ILP) is a linear program where each unknown variable is required to have integer values [Schrijver, 1998]. A Linear Programming (LP) is an optimization problem of the form:

$$\begin{aligned} & \min & c^T x \\ & \text{subject to} & A_1 x \leq b_1 \\ & A_2 x = b_2 \end{aligned}$$

where c^Tx is a cost or *objective* function, $A_1x \leq b_1$ and $A_2x = b_2$ are *constraints*, and x denotes a vector of *variables*. In addition, $c \in \mathbb{R}^n, b_i \in \mathbb{R}^{m_i}, A_i \in \mathbb{R}^{n \times m_i}, i = 1, 2$ are given and $x \in \mathbb{Z}^n$ is an n-vector to be determined. In other words, we try to find the minimum of a linear function over a feasible set defined by a finite number of linear constraints. It can be shown that a problem with linear equalities or linear inequalities (for instance \leq) can always be put in the above form, implying that this formulation is more general than it might look. An ILP problem is obtained from an LP problem by requiring that all entries of the solution vector x are integers. LP problems are "easy" to solve (they are in the complexity class P), whereas ILP problems are, in general, difficult (they are NP-hard) [Schrijver, 1998].

Example 1 Consider the following ILP

$$\begin{array}{ll} \textit{min} & -x-2y\\ \textit{subject to} & x+y+z_1=3\\ & x+z_2=2\\ & y+z_3=2\\ & x,y,z_i\geq 0 \end{array}$$

The optimal value of the ILP is when $(x, y, z_1, z_2, z_3) = (1, 1, 1, 1, 1)$ with value -3.

2.3 Cutting Plane Inference (CPI)

A MAP query corresponds to an optimization problem with linear constraints and a linear objective function. Hence, it can be formulated and solved as an instance of an integer linear program (ILP). [Riedel, 2012] introduced cutting plane inference as a meta algorithm that transforms an MLN into ILP. The basic idea of CPI is to add all constraints to the ILP that violate the current intermediate solution. This process is repeated until no (additional) violated ground clauses exist. An ILP solver resolves the conflicts by computing an optimal truth assignment for an MLN. Hence, the solution of the final ILP corresponds to the MAP state. It is necessary to execute several iterations as the intermediate solution changes after each iteration and more violated clauses might be detected. At the beginning of each CPI iteration it is necessary to determine the violated ground clauses \mathcal{G} that are specified by the MLN and are in conflict with the intermediate solution. A binary ILP variable $x_{\ell} \in \{0,1\}$ gets assigned to each grounded predicate occurring in a violated clause $g \in \mathcal{G}$. The value of the the variable x_{ℓ} is 1 if the respective literal ℓ is true and 0 when it is false. These variables are used to generate ILP constraints that are added to the ILP for each violated ground clause. For each clause $g \in \mathcal{G}$, we define $L^+(g)$ as the set of

ground atoms that occur unnegated in g and $L^-(g)$ as the set of ground atoms that occur negated in g. The transformation scheme depends on the weight $w_g \in \mathbb{R}$ of the violated clause g. It is also necessary to create a binary variable z_g for every g with $w_g \neq \infty$ that is used in the objective of the ILP. For every ground clause g with $w_g > 0$, the following constraint has to be added to the ILP.

$$\sum_{\ell \in L^{+}(g)} x_{\ell} + \sum_{\ell \in L^{-}(g)} (1 - x_{\ell}) \ge z_{g}$$

A ground atom ℓ that is set to false (true if it appears negated) by evidence will not be included in the ILP as it cannot fulfil the respective constraint. For every g with weight $w_g < 0$, we add the following constraint to the ILP:

$$\sum_{\ell \in L^+(g)} x_{\ell} + \sum_{\ell \in L^-(g)} (1 - x_{\ell}) \le (|L^+(g)| + |L^-(g)|) z_g$$

The variable z_g expresses if a ground formula g is true considering the optimal solution of the ILP. However, for every g with weight $w_g = \infty$ this variable can be replaced with 1 as the respective formula cannot be violated in any solution:

$$\sum_{\ell \in L^{+}(g)} x_{\ell} + \sum_{\ell \in L^{-}(g)} (1 - x_{\ell}) \ge 1$$

Finally, the objective of the ILP sums up the weights of the (satisfied) ground formulas:

$$\max \sum_{g \in \mathcal{G}} w_g z_g$$

The MAP state corresponds to the solution of the ILP in the last CPI iteration. It can be directly obtained from the solution as the assignment of the variables x_ℓ can be directly mapped to the optimal truth values for the ground predicates, i.e., $x_i = \texttt{true}$ if the corresponding ILP variable is 1 and $x_i = \texttt{false}$ otherwise. The MAP state of an \mathcal{EL}^{++} -LL TBox can be computed by a reduction into CPI.

2.4 $\mathcal{E}\mathcal{L}^{++}$ -LL

 \mathcal{EL}^{++} -LL (Log-linear \mathcal{EL}^{++}) is a probabilistic extension of \mathcal{EL}^{++} without nominals and concrete domains [Niepert et~al., 2011]. Each \mathcal{EL}^{++} -LL TBox axiom is either deterministic (i.e., axioms that are known to be true) or uncertain (i.e., axioms that have a degree of confidence). The uncertain axioms have associated weight. Formally, a \mathcal{EL}^{++} -LL TBox is given by $\mathcal{T}=(\mathcal{T}^D,\mathcal{T}^U)$, where \mathcal{T}^D and \mathcal{T}^U , is a set of pairs of $\langle S, w_S \rangle$ where S is an axiom and w_S is its real-valued weight, denote deterministic and uncertain axioms respectively.

The semantics of an \mathcal{EL}^{++} -LL TBox is given by a joint probability distribution over a *coherent* \mathcal{EL}^{++} TBox. Given TBoxes $\mathcal{T}=(\mathcal{T}^D,\mathcal{T}^U)$ and \mathcal{T}' over the same vocabulary, the probability of \mathcal{T}' is given by:

$$P(\mathcal{T}') = \begin{cases} \frac{1}{Z} \exp\left(\sum_{\{\forall (S, w_S) \in \mathcal{T}^U : \mathcal{T}' \models S\}} w_S\right) \\ \text{if } \mathcal{T}' \models \mathcal{T}^D \land \mathcal{T}' \not\models \bot \\ 0 \quad \text{otherwise} \end{cases}$$

In order to generate the most probable, coherent and classified TBox using MLN, \mathcal{EL}^{++} completion rules and \mathcal{EL}^{++} -LL TBox axioms are translated into FOL formulae.

In the following, we show how to extend \mathcal{EL}^{++} -LL with nominals, instances, and concrete domains.

3 Extending \mathcal{EL}^{++} -LL with Nominals, Instances and Concrete Domains

In [Niepert *et al.*, 2011], the authors claim that their approach is extensible to the Horn fragments of DLs (look [Krötzsch, 2011] for instance). To take advantage of this claim, we extend \mathcal{EL}^{++} -LL with probabilistic knowledge expressed through nominals, individuals, and concrete domains. The syntax of this extension (that we call \mathcal{MEL}^{++}) is the same as that of \mathcal{EL}^{++} -LL, basically, it is the syntax of \mathcal{EL}^{++} with weights attached to each uncertain axiom and assertion. An \mathcal{MEL}^{++} KB has two components: deterministic KB^D and uncertain KB^U knowledge bases. In order to provide semantics, we assume that KB^D is coherent. The semantics of *coherent* \mathcal{MEL}^{++} KBs is given by a probability distribution as defined below.

Definition 1 Given an \mathcal{MEL}^{++} knowledge base $KB = (KB^D, KB^U)$ over a vocabulary of N_C , N_R , N_F , and N_I , the semantics of a coherent $KB_i = (KB_i^D, KB_i^U)$ over the same vocabulary is given by a probability distribution:

$$P(KB') = \begin{cases} \frac{1}{Z} \exp\left(\sum_{\{\forall (o_j, w_j) \in KB^U : KB_i \models o_j\}} w_j\right) \\ \text{if } KB_i \models KB^D \land KB_i \not\models \bot \\ 0 \quad \text{otherwise} \end{cases}$$

Example 2 Consider an \mathcal{MEL}^{++} KB = (KB^D, KB^U):

$$\begin{split} \mathbf{KB}^D &= \{ \ Toddler \ \sqcap \ Adult \ \sqsubseteq \bot \}, \\ \mathbf{KB}^U &= \{ \langle Toddler \ \sqsubseteq \ \exists age. (\leq, 3), \ 0.8 \rangle, \end{split}$$

$$\langle \exists age.(\leq,3) \sqsubseteq Person, 0.7 \rangle, \\ \langle Toddler \sqsubseteq Adult, 0.1 \rangle, \langle age(john,2), 0.7 \rangle \}$$

The probabilities of the axioms and assertions can be computed as follows:

$$P(\{Toddler \sqsubseteq \exists age.(\leq,3)\}) = \frac{1}{Z} \exp(0.8)$$
$$P(\{Toddler \sqsubseteq Adult\}) = 0$$

$$P\Big(\{Toddler \sqsubseteq \exists age.(\leq,3), age(john,2),$$

$$\exists age.(\leq,3) \sqsubseteq Person\} \bigg) = \frac{1}{Z} \exp(2.2)$$

$$P(\{\}) = \frac{1}{Z} \exp(0)$$

$$P\big(\{Toddler \sqcap Adult \sqsubseteq \bot\}\big) = 1$$

$$Z = \exp(0.8) + \exp(2.2) + \exp(0.7) + \exp(0)$$

In order to derive the most probable, classified and coherent \mathcal{EL}^{++} ontology from an \mathcal{MEL}^{++} KB, we transform the KB, TBox completions rules [Baader *et al.*, 2005], concrete domains, and ABox completion rules [Krötzsch, 2011] into FOL formulae.

3.1 Nominals

(Un)certain axioms that contain nominals can be translated into FOL in MNL by using Definition 2. Inference in MNL can be done by converting the completion rule CR6 [Baader et al., 2005] into FOL and enforcing that each nominal $a_i \in N_I$ is distinct. Alternatively, unique name assumption for individuals names can be enforced by using the axiom $\{a\} \sqcap \{b\} \sqsubseteq \bot$ for all relevant individual names a and b. In addition, the transformation of TBox completion rules into FOL in MNL is given in Table 1.

By using nominals, instance knowledge can be added to an ABox.

3.2 ABox

Since the description logic \mathcal{EL}^{++} is equipped with nominals. ABox knowledge can be converted into TBox axioms. Thus, with nominals, ABox becomes syntactic sugar:

$$C(a) \Leftrightarrow \{a\} \sqsubseteq C, \ R(a,b) \Leftrightarrow \{a\} \sqsubseteq \exists R.\{b\}$$

Instance checking in turn is directly reducible to subsumption checking in the presence of nominals. There exist two ways to represent uncertain ABox assertions, i.e., C(a) and R(a,b), in MLN:

i. transform ABox assertions into TBox axioms using nominals as follows:

$$\langle C(a), w_1 \rangle \Leftrightarrow \langle \{a\} \sqsubseteq C, w_1 \rangle$$
$$\langle R(a, b), w_2 \rangle \Leftrightarrow \langle \{a\} \sqsubseteq \exists R. \{b\}, w_2 \rangle$$

iii. introduce two new predicates for each instance type as:

$$\langle C(a), w_1 \rangle \mapsto inst(a, C) \ w_1$$

 $\langle R(a, b), w_2 \rangle \mapsto rinst(a, R, b) \ w_2$

This approach requires transforming ABox completion rules into FOL, so as to generate classified ontologies.

In this paper, we consider the second approach (ii)¹. Next, we show how concrete domains are translated into the MLN framework.

3.3 Concrete Domains

Reasoning over uncertain concrete domains can be done by transforming the datatype predicates in the axioms and assertions into mixed integer programming as shown in [Straccia, 2012]. However, in this work, we introduce an efficient approach that transforms the predicates into a test function that evaluates to *true* or *false* based on the grounding generated by an extension of the CPI algorithm. Inference involving axioms that contain concrete domains can be done according to the deduction rules given below:

$$\frac{A \sqsubseteq B \quad B \sqsubseteq \exists F.(o, v)}{A \sqsubseteq \exists F.(o, v)}$$

$$\frac{A \sqsubseteq \exists F.(o_1, v_1) \quad \exists F.(o_2, v_2) \sqsubseteq B}{A \sqsubseteq B} \quad eval(o_1, v_1, o_2, v_2)$$

$$\frac{\exists F.(o, v_1) \sqsubseteq A \quad F(a, v_2)}{A(a)} \quad eval(o, v_1, =, v_2)$$

$$\frac{A(a) \quad A \sqsubseteq \exists F.(=, v)}{F(a, v)}$$

where eval(...) checks if all possible values of the first operator-value pair (o_1, v_1) are covered by the possible values of the second operator-value pair (o_2, v_2) , when so, it evaluates to true otherwise false. The function eval(...) is defined based on a datatype \mathcal{D} , i.e., \mathbb{N} or \mathbb{Z} or \mathbb{R} , and algebraic operators. Some of the algebraic comparisons, computed via eval(...), that are useful to determine inference are listed below:

$$\begin{array}{l} eval(\leq,v_1,<,v_2) \ := v_1 < v_2 \\ eval(\leq,v_1,\leq,v_2) \ := v_1 \leq v_2 \\ eval(=,v_1,<,v_2) \ := v_1 < v_2 \\ eval(=,v_1,\leq,v_2) \ := v_1 \leq v_2 \\ eval(=,v_1,=,v_2) \ := v_1 \leq v_2 \\ eval(=,v_1,\geq,v_2) \ := v_1 \geq v_2 \\ eval(=,v_1,\geq,v_2) \ := v_1 \geq v_2 \\ eval(\geq,v_1,\geq,v_2) \ := v_1 \geq v_2 \\ eval(\geq,v_1,\geq,v_2) \ := v_1 \geq v_2 \\ eval(\geq,v_1,>,v_2) \ := v_1 \geq v_2 \\ eval(\geq,v_1,>,v_2) \ := v_1 \geq v_2 \\ eval(>,v_1,>,v_2) \ := v_1 \geq v_2 \\ eval(>,v_$$

This function is computed on-demand after each CPI iteration as discussed in the next section. The translation of the deduction rules into FOL is given in Table 1 and Table 2.

Example 3 Consider an \mathcal{MEL}^{++} KB = $\{\langle 2YearOld \sqsubseteq \exists age.(=,2),0.7\rangle, \langle \exists age.(\leq,3) \sqsubseteq Toddler,0.8\rangle \}$ that contains axioms expressed using concrete domains. From the KB, the axiom $2YearOld \sqsubseteq Toddler$ can be inferred since $eval(o_1,v_1,o_2,v_2)$ is true, i.e., $eval(=,2,\leq,3):=2\leq 3$.

So far we have discussed how axioms and assertions can be translated into FOL. Next, we show how the most probable KB is derived using MAP inference.

4 Computing a Most Probable KB

To derive the most probable classified and coherent ontology from a weighted \mathcal{EL}^{++} KB, we proceed by transforming TBox and ABox completion rules, schema axioms, and assertions into function-free FOL formulae. The formulae corresponding to the translation of completion rules into FOL are shown in Table 1 and Table 2. The formulae from F_1 through F_9 are taken from [Niepert $et\ al.$, 2011]. Additionally, a bijective mapping function is provided in Definition 2 to transform axioms and assertions into formulae. Of particular interest for us is proposing a novel way to deal with concrete domains under MLN by modifying the Cutting Plane Inference (CPI) algorithm.

In \mathcal{EL}^{++} , it is possible to build incoherent TBox axioms due to the presence of the bottom concept \bot , for instance, consider the axiom $\{a\} \sqsubseteq \bot$, this cannot be satisfied by any interpretation. To filter out such incoherencies in models generated by MLN, we include the formula $\forall c: \neg sub(c, \bot)$ (formula F_9 in Table 1) to the translation of the completion rules into FOL. This technique has already been used in [Niepert et al., 2011].

Definition 2 [Mapping \mathcal{MEL}^{++} KB into Ground FOL predicates] The function φ translates a normalized \mathcal{MEL}^{++}

¹We leave a comparison of the two approaches as a future work.

```
F_1
         \forall c : sub(c, c)
F_2
         \forall c : sub(c, \top)
         \forall c, c', d : sub(c, c') \land sub(c', d) \Rightarrow sub(c, d)
F_3
F_4
         \forall c, c_1, c_2, d : sub(c, c_1) \land sub(c, c_2) \land int(c_1, c_2, d) \Rightarrow sub(c, d)
F_5
         \forall c, c', r, d : sub(c, c') \land rsup(c', r, d) \Rightarrow rsup(c, r, d)
F_6
         \forall c, r, d, d', e : rsup(c, r, d) \land sub(d, d') \land rsub(d', r, e) \Rightarrow sub(c, e)
F_7
         \forall c, r, d, s : rsup(c, r, d) \land psub(r, s) \Rightarrow rsup(c, s, d)
         \forall c, r_1, r_2, r_3, d, e : rsup(c, r_1, d) \land rsup(d, r_2, e) \land pcomp(r_1, r_2, r_3) \Rightarrow rsup(c, r_3, e)
F_8
F_9
         \forall c : \neg sub(c, \bot)
        \forall c, d, a, r : subNom(c, a) \land subNom(d, a) \land rsup(c, r, d) \rightarrow sub(c, d)
F_{10}
         \forall c, d, a, r, b : subNom(c, a) \land subNom(d, a) \land rsupNom(b, r, d) \rightarrow sub(c, d)
F_{11}
        \forall c, d, f, o, v : sub(c, d) \land rsupEx(d, f, o, v) \Rightarrow rsupEx(c, f, o, v)
F_{12}
F_{13}
         \forall c, d, f, o, v : rsupEx(c, f, o_1, v_1) \land rsubEx(f, o_2, v_2, d) \land eval(o_1, v_1, o_2, v_2) \Rightarrow sub(c, d)
```

Table 1: TBox completion rules.

```
F_{14}
        \forall x, A, B : inst(x, A) \land sub(A, B) \Rightarrow inst(x, B)
F_{15}
        \forall x, A_1, A_2, B : inst(x, A_1) \land inst(x, A_2) \land int(A_1, A_2, B) \Rightarrow inst(x, B)
        \forall x, y, R, A, B : rinst(x, R, y) \land inst(y, A) \land rsub(A, R, B) \Rightarrow inst(x, B)
F_{16}
        \forall x, y, R : rinst(x, R, y) \land inst(y, \bot) \Rightarrow inst(x, \bot)
F_{17}
        \forall x, y, R, S : rinst(x, R, y) \land psub(R, S) \Rightarrow rinst(x, R, y)
F_{18}
F_{19}
        \forall x, y, z, R_1, R_2, R_3 : rinst(x, R_1, y) \land rinst(y, R_2, z) \land pcomp(R_1, R_2, R_3) \Rightarrow rinst(x, R_3, z)
        \forall x, a, B : ninst(x, a) \land inst(x, B) \Rightarrow inst(a, B)
F_{20}
        \forall x, a, B : ninst(x, a) \land inst(a, B) \Rightarrow inst(x, B)
F_{21}
        \forall x, a, z, R : ninst(x, a) \land rinst(z, R, x) \Rightarrow rinst(z, R, a)
F_{22}
        \forall x, A, B : sub(\top, A) \land inst(x, B) \Rightarrow inst(x, A)
F_{23}
        \forall x, x', R, A, B : inst(x, a) \land rsup(A, R, B) \Rightarrow rinst(x, R, x')
F_{24}
        \forall x, x', R, A, B : inst(x, a) \land rsup(A, R, B) \Rightarrow inst(x', B)
F_{25}
        \forall f, op, v, C : rsupEx(f, op, v, C) \land rinst(a, f, v') \land eval(v, op, v') \Rightarrow inst(a, A)
F_{26}
        \forall a, A, f, v : inst(a, A) \land rsubEx(A, f, =, v) \Rightarrow rinst(a, f, v)
F_{27}
        \forall a, A_1, A_2, f, v : inst(a, A_1) \land inst(a, A_2) \land intEx(A_1, A_2, f, op, v) \Rightarrow rinst(a, f, v)
F_{28}
```

Table 2: ABox completion rules.

knowledge base KB into FOL formulae in MLN as follows:

```
C(a) \mapsto \operatorname{inst}(a, C)
R(a, b) \mapsto \operatorname{rinst}(a, R, b)
A \sqsubseteq \bot \mapsto \operatorname{sub}(A, \bot)
\top \sqsubseteq C \mapsto \operatorname{sub}(\top, C)
A \sqsubseteq \{c\} \mapsto \operatorname{sub}\operatorname{Nom}(A, \{c\})
\{a\} \sqsubseteq \{c\} \mapsto \operatorname{sub}(\{a\}, \{c\})
A \sqsubseteq C \mapsto \operatorname{sub}(A, C)
A \sqcap B \sqsubseteq C \mapsto \operatorname{int}(A, B, C)
\exists R. A \sqsubseteq C \mapsto \operatorname{rsub}(A, R, C)
```

```
A \sqsubseteq \exists F.(o,v) \mapsto \operatorname{rsupEx}(A,F,o,v)
\exists F.(o,v) \sqsubseteq A \mapsto \operatorname{rsubEx}(F,o,v,A)
R_1 \sqsubseteq R_2 \mapsto \operatorname{psub}(R_1,R_2)
R_1 \circ R_2 \sqsubseteq R \mapsto \operatorname{pcom}(R_1,R_2,R)
\operatorname{int}(\{a_i\},\{a_j\},\bot) \quad \textit{where } a_i,a_j \in \operatorname{N_I} \textit{ and } i \neq j
\textit{where } a,b,c \in \operatorname{N_I},\ A,B,C \in \operatorname{N_C},\ R,R_1,R_2 \in \operatorname{N_R},\ F \in \operatorname{N_F},\ o \in \{<,\leq,>,\geq,=\},\ \textit{and } v \in \mathbb{R} \ \textit{(set of real numbers)}.
```

 $A \sqsubseteq \exists R.B \mapsto \text{rsup}(A, R, B)$

Lemma 1 The translation of an \mathcal{EL}^{++} KB into FOL and vice versa can be done in polynomial time in the size of the knowledge base [Lukasiewicz et al., 2012].

From the above Lemma, we see that the translation of \mathcal{MEL}^{++} KB completion rules, axioms, and assertions into FOL in MLN does not affect the complexity of inference in MLN. Besides, as *typed variables* and *constants* greatly reduce size of ground Markov nets. We introduce types to all of the predicates shown in Tables 1 and Table 2.

Theorem 1 Given an \mathcal{MEL}^{++} ontology $KB = (\mathcal{T}, \mathcal{A})$ and $KB' \subseteq KB$, a Herbrand interpretation \mathcal{H} is a model of KB', i.e., $\mathcal{H} \models KB'$ if and only if there exist a mapping function φ such that $\varphi(\mathcal{H}) \models KB'$.

So far we have introduced a mapping function φ for KB assertions and axioms and completion rules as formulae (F_{1} – F_{28}). The next step requires using MAP inference of MLN to obtain the most probable ontology of a given \mathcal{MEL}^{++} KB.

4.1 Maximum A-Posteriori Inference (MAP)

In order to deal with \mathcal{MEL}^{++} datatypes, we introduced a predicate called eval(...) in the translation of \mathcal{EL}^{++} completion rules into FOL, depicted in Table 1 and Table 2. The truth value of eval(...) is computed by evaluating the logical expressions corresponding to datatypes in an \mathcal{MEL}^{++} KB. For instance, consider the eval(...) predicate in Example 3. In the following, we show how the expression $(=, 2) \subseteq (\leq, 3)$, operator-value pair coverage, i.e., is evaluated by extending the CPI algorithm. Thus, we propose an extension of CPI by incorporating algebraic expressions. In particular, our extension addresses a limitation of MLN with respect to concrete domains. In general, all (numerical) values are represented as constants in MLN. The only semantics that are related to constants might be the type to which they belong. This enables more efficient grounding and leads to smaller MLNs. However, this does hardly cover the characteristics of numerical values. Therefore, we exploit the iterative character of CPI in order to evaluate numerical (in)equalities. The extension can be considered as additional features that are only used ondemand. It is formula-specific as it affects the ground values and the truth value of specific constraints. Hence, it can be implemented as an extension of the detection of the violated

The algorithm identifies at the beginning of each CPI iteration for each formula all violated groundings considering the current intermediate solution. Each of the violated ground clauses has to be translated and added to the ILP. Therefore, an ILP variable is generated for each ground predicate as well as additional ILP constraints. Datatype ground predicates eval(...) appear during this process as any other predicates. However, we exploit there semantics to decide whether eval(...) predicates evaluate to true or false. Depending on the result of the evaluation of the attached boolean expression of the respective predicate, we decide whether it is necessary to add the violated ground clause to the ILP. For instance, if the datatype predicate is positive (negative) and it appears without negation (or negation) in the formula, we do not add the ground clause to the ILP as it is not violated in the current iteration. Otherwise, we need to add the clause to the ILP but leave out the datatype ground predicates as they can not fulfil the violated clause, i.e., the respective literal is false due to evidence. Hence, we do not introduce ILP variables for datatype predicates as they will not be added to the ILP. Instead, we compute the truth value of the datatype predicates on-the-fly and only on-demand. Hence, the proposed approach improves the efficiency of processing numerical predicates in a Markov logic solver without sacrificing the performance. We implemented this algorithm as an extension to the MLN inference engine ROCKIT² [Noessner *et al.*, 2013]. We leave out testing this implementation with different ontologies as a future work.

Theorem 2 *Given the following:*

- an \mathcal{MEL}^{++} knowledge base $KB = (KB^D, KB^U)$ formed from a vocabulary containing a finite set of individuals N_I , concepts N_C , features N_F , and roles N_R ,
- HB as a Herbrand base of the formulae F in Table 1 and Table 2 over the same vocabulary,
- G_1 as a set of ground formulae constructed from KB^D,
- G_2 as a set of ground formulae constructed from KB^U , the most probable coherent and classified ontology is obtained with:

$$\varphi^{-1}(\hat{I}) = \underset{\text{HB} \supseteq I \models G_1 \cup F}{\operatorname{arg\,max}} \left(\sum_{(o_i, w_i) \in G_2 : I \models o_i} w_j \right)$$

From Theorem 2 and the results in [Roth, 1996], finding the most probable, classified and coherent \mathcal{MEL}^{++} KB is in NP. The *hardness* of this complexity bound can be obtained by reducing partial weighted MaxSAT problem into an \mathcal{MEL}^{++} MAP query. Consequently, the MAP problem for \mathcal{MEL}^{++} is NP-hard.

5 Conclusion

In this work, we have extended \mathcal{EL}^{++} -LL into \mathcal{MEL}^{++} with nominals, concrete domains and instances. In particular, we proposed an extension to the CPI algorithm in order to deal with reasoning under uncertain concrete domains. We have implemented the proposed approach and planned to carry out experiments in the future. We will also investigate to extend the proposed approach to other datatypes such as Date, Time, and so on.

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²https://code.google.com/p/rockit/

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